

Application Note 006
Version 001
27 March 2017

Network Control of an ABB ACH550 VFD

The concept of interacting with a VFD by using an Industrial Networking Protocol – such as Modbus or EtherNet/IP – is vastly superior to legacy methods that use discrete I/O wired to the terminal block. Why? Because there is so much more information available to the Control System when communicating directly with the VFD’s microprocessor.

Network-available feedback tags include Speed (Hz), Power (HP, KW), Energy (MWH), Current (A), Voltage (V), Temperature (°), and Fault Information. Furthermore, the network wiring is arguably simpler than discrete signal wiring – since it only relies upon a single twisted pair or Ethernet cable. On the other hand, extra know-how is required to collect and process the extra information. Therefore, in order to clarify and simplify the theory and practice of controlling and monitoring a VFD across a network, Navionics Research has developed a library of Application Notes, each designed to address networking techniques specific to a particular manufacturer. Notes are currently available for Allen Bradley (Modbus), ABB (Modbus), Eaton (Modbus), and Toshiba (Toshiba Proprietary Protocol). Others may be forthcoming.

ABB ACH550

This document was created to address the specifics of the ABB ACH550 VFD using the Modbus/RTU protocol over RS-485, which is included standard on all models within the ACH550 family. For brevity, we will refer to this drive as the “ACH550”.



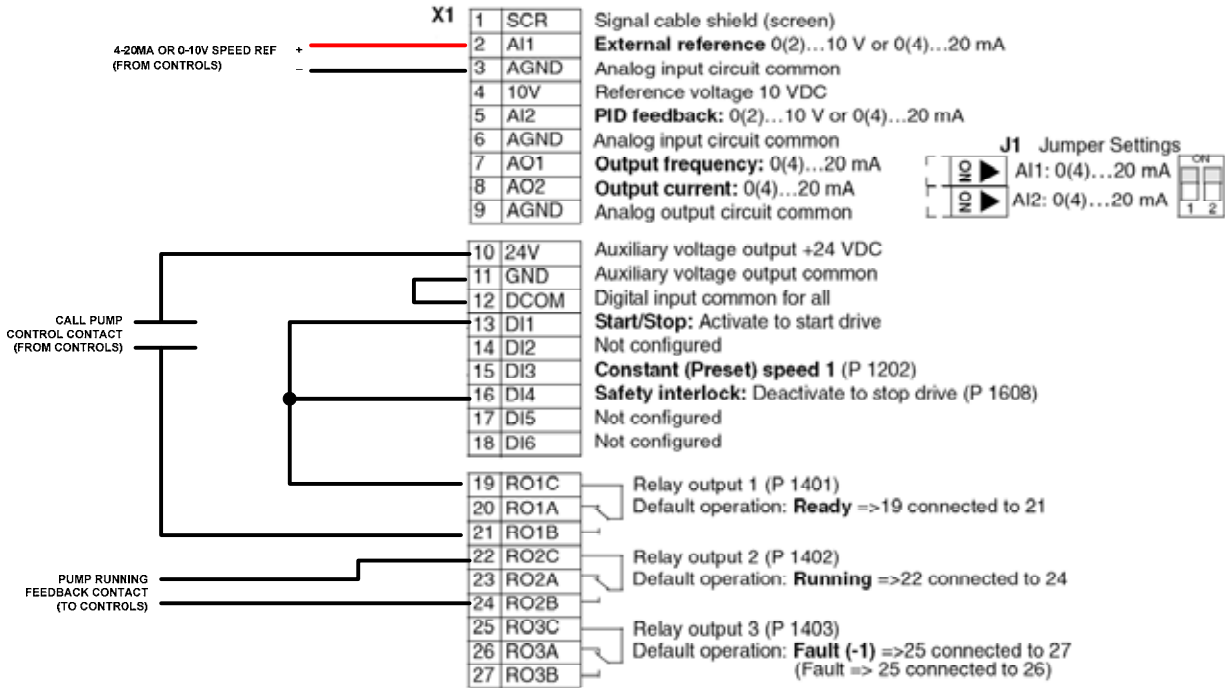
First, the following documents should be available for reference:

[ABB ACH550 Manual](#)

[ABB ACH550 Fieldbus Manual](#)

Signal Wiring

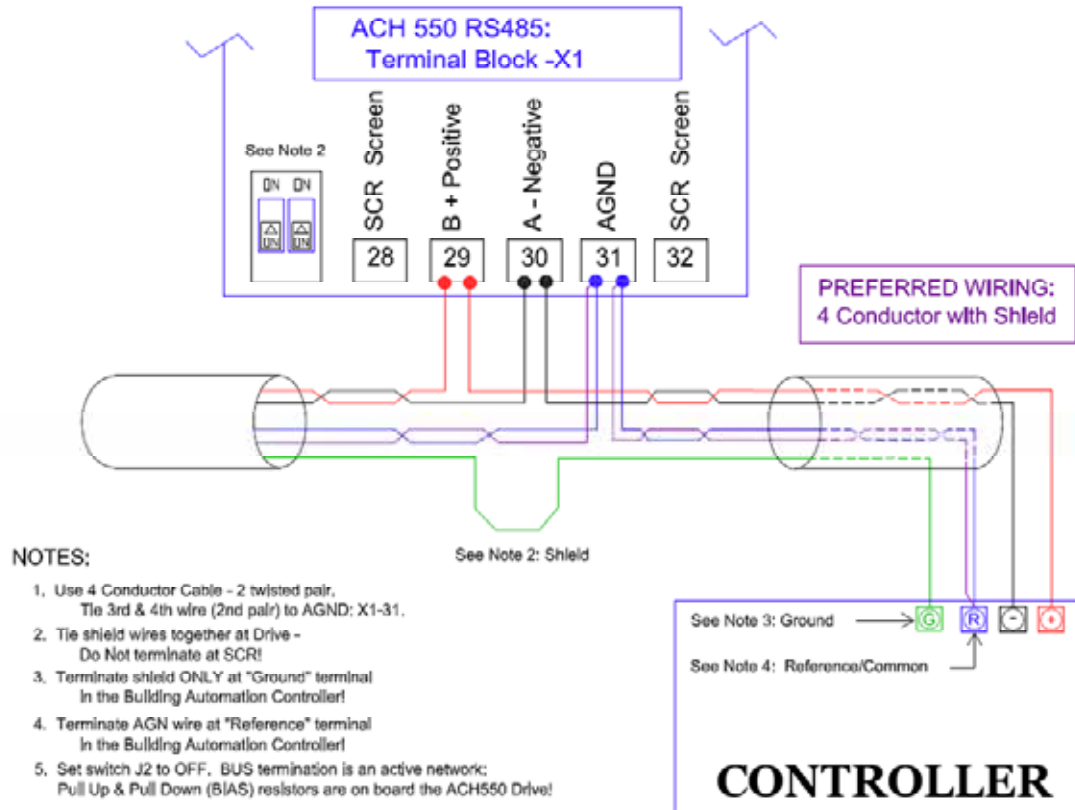
The VFD should be wired for Modbus/RTU Control/Monitoring. Note that the ACH550's RS-485 terminals are labeled in accordance with the most predominant North American Standard: 'A' is '-', and 'B' is '+'.
 In addition to the Modbus/RS-485 terminals, wiring is provided for backup discrete controls with analog speed reference in case of communication bus failure: A single dry contact input is to provide a run signal to VFD Digital Input #1, and a 24V output signal via VFD Internal Relay #1 is to denote that the drive running.



Terminal Block Wiring Diagram.

Note: Jumper J1 should be set to match the Reference Signal Type.

Preferred wiring diagram



Keypad: Basic Configuration

The VFD should be configured using the Wizard Setup Screens with the Motor Nameplate Values.

9902	Application Macro	1=HVAC (Default)	_____
9904	Motor Control Mode	3=SCALAR/FREQ (Default)	_____
9905	Motor NP Volts	Motor Nameplate Rated Volts	_____
9906	Motor OL Current	Maximum Allowable Motor Current	_____
9907	Motor NP Hertz	Motor Nameplate Rated Frequency	_____
9909	Motor NP Power	Motor Nameplate Rated Horsepower	_____

Keypad: Communication & Terminal Block Configuration, Part I

The VFD should be set up with the following parameters:

9802	Protocol Selection	1	1=MODBUS (Default)
1001	EXT1 Start Command	1	1=DII(Default). Dependent upon terminal block wiring.
1002	EXT2 Start Command	10	1=DII (Default), 10=MODBUS/COMM
1102	EXT1/EXT2 Sel	7	0=EXT1 (Default), 7=EXT2
1103	REF1 Sel	1	1=AI1 (Default)
1106	REF2 Sel	8	19=PID1OUT (Default), 8 = MODBUS/COMM
1601	Run Enable	0	0=None (Default)
1604	Fault Reset Sel	0	0=KEYPAD (Default)
1609	Start Enable 2	0	0=None (Default)
3018	Comm Fault Action	0	0=No Action
3019	Comm Fault Time	60	10=Default, 60 sec=Preferred
5302	Modbus Device ID	101	MODBUS Address – Set per user needs: 101,102,... ____
5303	Modbus Baud	9.6	9600 bps
5304	Modbus Parity	0	1 = 8N2 (Default) 0 = 8N1 – 8 Data Bits / N=No Parity / 1 Stop Bit
5305	Modbus Ctrl Profile	0	0 = ABB DRV LIM (For Maximum Backwards Compatibility)
5312	40007 Register Map	105	105=TORQUE
5313	40008 Register Map	106	106=POWER
5314	40009 Register Map	107	107=BUS VOLTS
5315	40010 Register Map	401	401=LAST FAULT
5316	40011 Register Map	109	109=OUTPUT VOLTS
5317	40012 Register Map	110	110=VFD TEMPERATURE

Note! – The VFD must now be power-cycled for the above settings to take effect.

After this initial Modbus configuration is performed, much of the additional Modbus configuration will be performed by the connected Master PLC via the communication port. In fact, Modbus configuration via the PLC is more desirable for many parameters, since parameters written using Modbus are volatile by default – meaning that they are not stored into the VFD’s nonvolatile memory unless explicitly commanded as such. Therefore, certain parameters specific to network-operation can be discarded simply by rebooting the VFD with the Master PLC disconnected from the VFD network port.

VFD Parameters Monitored Via MODBUS:

Volatile Modbus Register Changes: The remaining parameters are controlled by the Master PLC. Again, please note that all parameter changes made by the Master PLC are discarded upon reboot of the ACH550 VFD. This fact is utilized to allow for two distinct operational control modes.

Post VFD Boot-Up Delay: It is important that the VFD be allowed to fully boot up before writing to the VFD's Modbus registers. A 15 second delay has been observed to be more than sufficient.

Modbus Addressing: ABB Drive Parameters may be accessed (read/write) via Modbus communications. For example, ABB Parameter 1001 is hosted at Modbus Address 41001, which is often referenced as Modbus Address 1000 in Zero-Based Modbus Addressing Nomenclature.

REGISTER

(ZERO-BASED)

CONTENTS

0	CONTROL WORD
1	REFERENCE 1 (FROM EXT1)
2	REFERENCE 2 (FROM EXT2)
3	STATUS WORD
4	OUTPUT FREQUENCY
5	OUTPUT CURRENT
6	TORQUE
7	POWER
8	BUS VOLTS
9	LAST FAULT
10	OUTPUT VOLTS
11	VFD TEMPERATURE

STATUS WORD DETAIL (BITMAP)

0	RDY_ON	1 = Ready to Operate, 0 = Emergency OFF
1	RDY_RUN	1 = Operating, 0 = Emergency OFF
2	RDY_REF	1 = Operating, 0 = Emergency STOP
3	TRIPPED	1 = Operation Enabled, 0 = Operation Inhibited
4	OFF_2_STA*	
5	OFF_3_STA*	1 = RFG Out Enabled, 0 = RFG Out Hold
6	SWC_ON_INHIB	1 = RFG Input Enabled, 0 = RFG Input Force to Zero
7	ALARM	1 = Fault Reset, 0 = Continue Normal Operation
8	AT_SETPOINT	
9	REMOTE	
10	ABOVE_LIMIT	
11	EXT2	1 = Select EXT2 Control, 0 = Select EXT1 Control
12	RUN_ENABLE	
13	-N/A-	
14	-N/A-	
15	-N/A-	

VFD Parameters Controlled Via MODBUS:

REGISTER

(ZERO-BASED)

CONTENTS

0	CONTROL WORD
2	SPEED REFERENCE 2

CONTROL WORD DETAIL (BITMAP)

0	OFF1 CONTROL	1 = Ready to Operate, 0 = Emergency OFF
1	OFF2 CONTROL	1 = Operating, 0 = Emergency OFF
2	OFF3 CONTROL	1 = Operating, 0 = Emergency STOP
3	INHIBIT OPERATION	1 = Operation Enabled, 0 = Operation Inhibited
4	-UNUSED-	
5	RAMP HOLD	1 = RFG Out Enabled, 0 = RFG Out Hold
6	RAMP IN ZERO	1 = RFG Input Enabled, 0 = RFG Input Force to Zero
7	RESET	0→1 = Fault Reset, 0 = Continue Normal Operation
8	-UNUSED-	
9	-UNUSED-	
10	-UNUSED-	
11	EXT CTRL LOC	1 = Select EXT2 Control, 0 = Select EXT1 Control
12	-UNUSED-	
13	-UNUSED-	
14	-UNUSED-	
15	-UNUSED-	

Backup/Alternative VFD Control Via Terminal Block

How should the system be configured to handle a Modbus communication failure? First and foremost, the VFD should be configured to shut down if it stops receiving commands from the Master PLC. A 60 second timeout should be sufficient for this purpose. When the VFD stops due to comm loss, it will show a Fault Code 28.

After a Modbus communication fault is detected, NRI's standard backup control method consists of parallel, discrete (ON/OFF) control circuitry. The activation of this circuitry requires the operator to perform the following steps:

1. REBOOT THE VFD (CLEARS ALL RAM-ONLY SETTINGS)
2. CLEAR THE VFD FAULT AT THE KEYPAD
3. MAKE SURE THE VFD IS IN "AUTO" MODE (ALLOWS REMOTE CONTROL).
4. ACTIVATE MASTER PLC SETPOINT:

```
DISCRETE_VFD_CONTROL = YES/TRUE  
..or..  
NETWORK_VFD_CONTROL = NO/FALSE
```

The parallel, discrete control circuitry consists of three pairs of low-voltage wires: One for ON/OFF control of the drive, one for SPEED REFERENCE, and one for FEEDBACK/MONITORING. Through pair 1, a single dry contact will provide the run signal to the drive. If a speed reference pair (4-20mA or 0-10VDC) is provided, then the speed can be modulated. If not, then the VFD can be set to run at a user-defined PRESET SPEED. Through the final pair, a single contact output will provide RUN feedback to the Master PLC: When the ACH550 is "At Desired Frequency", a 24VDC signal will be transmitted. Until the Modbus communication link is re-established/repared, this method allows for the VFD to run ON/OFF based on an analog speed reference, or based upon a preset speed with controlled ramp-up and ramp-down times. Please note that when a VFD is configured for preset speed, the VFD will run only at a single speed, and that no speed throttling will occur in this mode.

Detailed VFD Monitoring

Now that network communication to the ACH550 has been achieved, the PLC programmer now has READ access to valuable VFD internal information.

Available DISCRETE tags for reading include (not a complete list):

```
VFD_READY  
VFD_ACTIVE (RUNNING)  
VFD_ALARM  
VFD_FAULTED  
VFD_AT_REFERENCE_SPEED
```

Available ANALOG tags for reading include (not a complete list):

```
VFD_OUTPUT_SPEED  
VFD_OUTPUT_AMPS  
VFD_OUTPUT_VOLTS  
VFD_DC_BUS_VOLTS  
VFD_OUTPUT_POWER_KW  
VFD_ENERGY_KWH  
VFD_TEMPERATURE  
VFD_ACTIVE_FAULT_CODE
```

Feedback Control Strategies

In a Water Utility, the VFD will typically be installed to control the speed of a pump motor. Available telemetry data may include pump discharge pressure, pump suction pressure, pump rate-of-flow, in addition to the data available from the drive itself. This extra data, when combined with the VFD control algorithm, may be used to implement closed-loop feedback control strategies. For example, an upper limit may be placed on the pump discharge pressure – or a lower limit on the pump suction pressure – or both. Other possibilities are to implement an upper limit on the rate-of-flow, or an upper limit on the power consumption. In any of these cases, the speed of the VFD will be throttled up or down in order to maintain the pressures and/or flow and/or power consumption within the desired envelope.

Cavitation Traps

Ideally, pump “no flow” conditions are detected by monitoring a flow meter. In situations where a flow meter is not available, and because the ACH550 provides realtime power consumption of the pump motor to the Master PLC, it is possible that the PLC can detect and/or alarm cavitation conditions – situations where the pump is not moving water as evidenced by the power consumption of the motor falling below the normal range.

Feedback Control

In a Water Utility, the VFD will typically be installed to control the speed of a pump motor. Available telemetry data may include pump discharge pressure, pump suction pressure, and pump rate-of-flow. This extra data, when combined with the VFD, may be used to implement closed-loop feedback control

VFD Reset Via Modbus:

Because the ACH550 provides actual VFD fault information to the Master PLC, this information can be alarmed and the operator notified of the problem. The information is transmitted as a decimal fault code, and the Operator may refer to the following document to decode the fault:

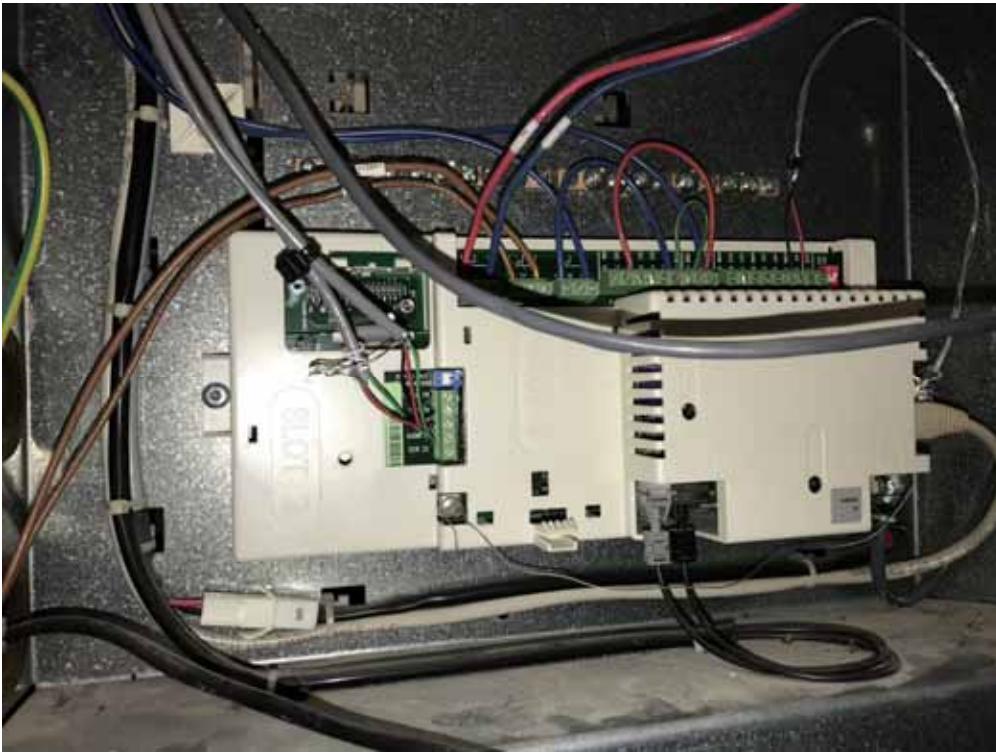
https://wireless-telemetry.com/PDF/ABB_VFD_Fault_Codes.pdf

Alternatively, the ABB ACH550 User Manual can be referenced to decode fault information.

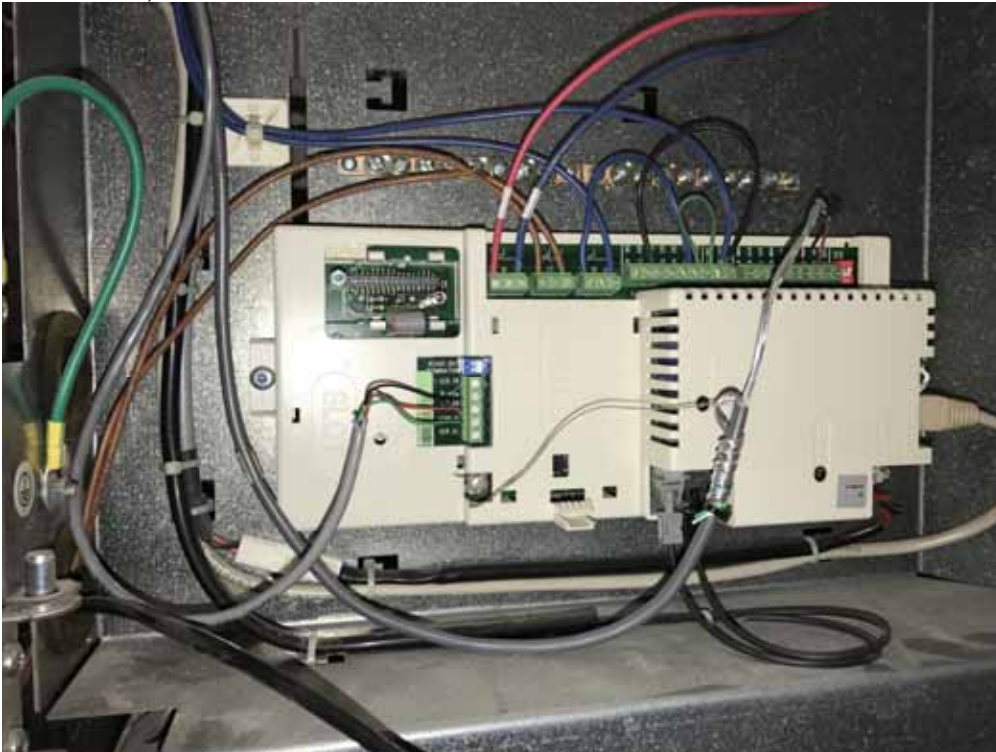
After decoding the fault, the Operator may reset the fault remotely using a provided “one-shot” pushbutton setting within the Telemetry Control System.



**An ABB Model ACH550 VFD.
At a Water Plant, Feeding a 250HP High Service Pump.**



VFD No. 1, Modbus Address 11.



VFD No. 2, Modbus Address 12. Note the 120 Ohm Termination Resistor Activated.



Configuration Keypad for ABB Model ACH550 VFD

Sample Generic Control Logic Source Code with VFD High-Service Pump Control

```

$NCH - Plant - ioz.15 (installed)
  4      # Number of Discrete Setpoints
 18      # Number of Analog Setpoints
  8      # Number of Integer Setpoints
 12      # Number of Discrete Input Modules
 12      # Number of Analog Input Modules
  0      # Number of Integer Input Modules
 22      # Number of Discrete Flag States
 20      # Number of Analog Flag States
  9      # Number of Integer Flag States
 12      # Number of Relay Output Modules
 12      # Number of Analog Output Modules
# Remote Setup Information ... (No Blank Lines Allowed...)
  4      # Number of Dependent Sites (Dependent Sites Follow)
 012     # Intake Pump Station
 001     # 1 Elev Tank
 013     # 13 Elev Tank
 014     # 14 Elev Tank
# Variable Name Definitions ... (Blank Lines Allowed...)

#
# Raw->Head Tank->Claricones->Filters->150KG C/W->Xfer Pmps->1MG GST
#
#
# MODBUS I/O MODULES...
#
# M_SIU - MODBUS FCN 3 INPUT, SHORT INTEGER UNSIGNED (16 BIT)
# M_SIS - MODBUS FCN 3 INPUT, SHORT INTEGER SIGNED (16 BIT)
# M_LIU - MODBUS FCN 3 INPUT, LONG INTEGER UNSIGNED (32 BIT)
# M_LIS - MODBUS FCN 3 INPUT, LONG INTEGER SIGNED (32 BIT)
# M_FI - MODBUS FCN 3 INPUT, FLOATING POINT (32 BIT)
#
# ALIAS INFL_METER_MODULE M_LIU 4 0
# ALIAS INFL_FLOW_MODULE M_LIS 4 4
# ALIAS INFL_METER_FAULT_MODULE M_SIU 4 14
# ALIAS EFFL_METER_MODULE M_LIU 5 0
# ALIAS EFFL_FLOW_MODULE M_LIS 5 4
# ALIAS EFFL_METER_FAULT_MODULE M_SIU 5 14
# ALIAS GST_PSI_MODULE M_FI 1 2
# ALIAS CLEARWELL_PSI_MODULE M_FI 2 2
# ALIAS EFFL_PSI_MODULE M_FI 3 2
#
# ABB VFD's MODBUS...
# HIGH SVC PUMP NO. 1, ADDR=11
# HIGH SVC PUMP NO. 2, ADDR=12
# ALIAS VFD1_SPD_RAWA M_SIU 11 102
# ALIAS VFD1_SPD_RAWB M_SIU 11 4
# ALIAS VFD2_SPD_RAWA M_SIU 12 102
# ALIAS VFD2_SPD_RAWB M_SIU 12 4

```

#EIG

GRAYHILL I/O MODULES...
#

ALIAS	HS1_FB_MODULE	LDM	0
ALIAS	HS2_FB_MODULE	LDM	1
ALIAS	XF1_FB_MODULE	LDM	2
ALIAS	XF2_FB_MODULE	LDM	3
ALIAS	POWER_OK_MODULE	LDM	4
ALIAS	GEN_FB_MODULE	LDM	5
ALIAS	GEN_LOFUEL_MODULE	LDM	6

ALIAS	HS1_SSR	LDR	0
ALIAS	HS2_SSR	LDR	1

ALIAS	HS1_SPEED_MODULE	LAOM	4
ALIAS	HS2_SPEED_MODULE	LAOM	5
ALIAS	XF1_SPEED_MODULE	LAOM	6
ALIAS	XF2_SPEED_MODULE	LAOM	7

SETPOINTS...
#

ALIAS	ALTERNATE_HI_SVC	LDS	0
ALIAS	HI_SVC_VFD_NETWORKING	LDS	1
ALIAS	HI_SVC1_RESET_ONESHOT	LDS	2
ALIAS	HI_SVC2_RESET_ONESHOT	LDS	3

ALIAS	HI_SVC_MINSPEED_%	LAS	0
ALIAS	HI_SVC_MAXSPEED_%	LAS	1
ALIAS	HI_SVC_FAILOVER_SPEED_%	LAS	2
ALIAS	EFFL_LIMIT_PSI	LAS	3
ALIAS	HI_SVC_GAIN	LAS	4
ALIAS	HI_SVC_MAXSTEP	LAS	5
ALIAS	EFFL_FLOW_DETECT_GPM	LAS	6
ALIAS	INFL_FLOW_DETECT_GPM	LAS	7
ALIAS	TIMER_1_START_HOUR	LAS	8
ALIAS	TIMER_1_STOP_HOUR	LAS	9
ALIAS	TIMER_2_START_HOUR	LAS	10
ALIAS	TIMER_2_STOP_HOUR	LAS	11
ALIAS	TIMER_3_START_HOUR	LAS	12
ALIAS	TIMER_3_STOP_HOUR	LAS	13
ALIAS	PRESSURE_MODE_ON_PSI	LAS	14
ALIAS	PRESSURE_MODE_RUNTIME_HRS	LAS	15
ALIAS	LOW_GST_FT	LAS	16
ALIAS	LOW_GST_RELEASE_FT	LAS	17

ALIAS	CALL_INTAKE_1{OFF-ON}	LIS	0
ALIAS	CALL_INTAKE_2{OFF-ON}	LIS	1
ALIAS	HI_SVC_1{AUTO-ON-OFF}	LIS	2
ALIAS	HI_SVC_2{AUTO-ON-OFF}	LIS	3
ALIAS	HI_SVC_MODE{RADIO-PRESS-TIMER}	LIS	4
ALIAS	HI_SVC_FAILOVER{PRESS-TIMER}	LIS	5
ALIAS	LEAD_HI_SVC{P1-P2}	LIS	6
ALIAS	LAG_HI_SVC{P1-P2}	LIS	7

D1 // ON=GREEN , OFF=BLANK
D2 // ON=RED/BLINKING , OFF=BLANK

```

# D3 // ON=GREEN , OFF=RED/BLINKING
# D4 // ON=GREEN/BLINKING , OFF=BLANK
#
# LOCAL FLAGS...
#

DISPL_D3 POWER LDF 0
DISPL_D4 CALL_INTAKE_1 LDF 1
DISPL_D4 CALL_INTAKE_2 LDF 2
DISPL_D4 HI_SVC_PUMP_1 LDF 3
DISPL_D4 HI_SVC_PUMP_2 LDF 4
DISPL_D3 RADIO_MODE LDF 5
DISPL_D2 PRESSURE_MODE LDF 6
DISPL_D2 TIMER_MODE LDF 7
$BLANK

DISPL_D4 XFER_PUMP_1 LDF 8
DISPL_D4 XFER_PUMP_2 LDF 9
$BLANK

DISPL_D2 LOW_GST LDF 10
DISPL_D2 GENERATOR LDF 11
DISPL_D2 GENERATOR_LO_FUEL LDF 12
DISPL_D2 COMM_FAIL_TO_TOWERS LDF 13
DISPL_D2 COMM_FAIL_TO_INTAKE LDF 14
$BLANK 3

DISPL_D2 EFFL_XDUCER_FAIL LDF 15
DISPL_D2 CLEARWELL_XDUCER_FAIL LDF 16
DISPL_D2 GST_XDUCER_FAIL LDF 17
$BLANK

DISPL_D2 HI_SVC_PUMP_1_FAIL LDF 18
DISPL_D2 HI_SVC_PUMP_2_FAIL LDF 19
DISPL_D2 HI_SVC1_VFD_COMM_FAIL LDF 20
DISPL_D2 HI_SVC2_VFD_COMM_FAIL LDF 21
$BLANK

DISPL EFFL_PSI LAF 0
DISPL EFFL_FLOW_GPM LAF 1
DISPL HI_SVC_VFD_SPEED_% LAF 2
$BLANK

DISPL CLEARWELL_FT LAF 3
DISPL CLEARWELL_KGAL LAF 4
$BLANK

DISPL GST_FT LAF 5
DISPL GST_KGAL LAF 6
DISPL INFL_FLOW_GPM LAF 7
DISPL PROCESS_FLOW_GPM LAF 8
$PAGE

DISPL HI_SVC1_KW LAF 9
DISPL HI_SVC2_KW LAF 10
DISPL HI_SVC1_GPK LAF 11
DISPL HI_SVC2_GPK LAF 12
DISPL HI_SVC1_DEGF LAF 13
DISPL HI_SVC2_DEGF LAF 14
DISPL HI_SVC1_FAULT_CODE LAF 15
DISPL HI_SVC2_FAULT_CODE LAF 16
$BLANK 2

DISPL UTIL_AB_VOLTS LAF 17

```

DISPL	UTIL_BC_VOLTS	LAF	18	
DISPL	UTIL_CA_VOLTS	LAF	19	
\$BLANK 7				
DISPL	EFFL_METER_GAL	LIF	0	
DISPL	INFL_METER_GAL	LIF	1	
DISPL	PROCESS_METER_GAL	LIF	2	
DISPL	HI_SVC_1_RUNTIME_MIN	LIF	3	
DISPL	HI_SVC_2_RUNTIME_MIN	LIF	4	
DISPL	XFER_PUMP_1_RUNTIME_MIN	LIF	5	
DISPL	XFER_PUMP_2_RUNTIME_MIN	LIF	6	
DISPL	LEAD_HI_SVC_PUMP	LIF	7	
DISPL	RTU_UPTIME_MIN	LIF	8	
\$PAGE				
#				
# REMOTE FLAGS...				
#				
DISPL_D3	COMM_TO_INTAKE	VLD	0	
DISPL_D4	INTAKE_PUMP_1	RDF	0	1
DISPL_D4	INTAKE_PUMP_2	RDF	0	2
\$BLANK				
DISPL_D3	COMM_TO_TWR01	VLD	1	
DISPL	TWR01_LEVEL_FT	RAF	1	0
DISPL	TWR01_LEVEL_KGAL	RAF	1	1
DISPL	TWR01_INFL_PSI	RAF	1	2
\$BLANK				
DISPL_D4	TWR01_CALL_PLANT	RDF	1	1
DISPL_D4	TWR01_FULL	RDF	1	2
DISPL_D4	TWR01_VALVE_OPEN	RDF	1	4
DISPL_D2	TWR01_XDUCER_FAIL	RDF	1	10
\$BLANK				
DISPL_D3	COMM_TO_TWR13	VLD	2	
DISPL	TWR13_LEVEL_FT	RAF	2	0
DISPL	TWR13_LEVEL_KGAL	RAF	2	1
DISPL	TWR13_INFL_PSI	RAF	2	2
\$BLANK 2				
DISPL_D4	TWR13_CALL_PLANT	RDF	2	1
DISPL_D4	TWR13_FULL	RDF	2	2
DISPL_D4	TWR13_VALVE_OPEN	RDF	2	4
DISPL_D2	TWR13_XDUCER_FAIL	RDF	2	10
\$BLANK				
DISPL_D3	COMM_TO_TWR14	VLD	3	
DISPL	TWR14_LEVEL_FT	RAF	3	0
DISPL	TWR14_LEVEL_KGAL	RAF	3	1
DISPL	TWR14_INFL_PSI	RAF	3	2
\$BLANK				
DISPL_D4	TWR14_CALL_PLANT	RDF	3	1
DISPL_D4	TWR14_FULL	RDF	3	2
DISPL_D4	TWR14_VALVE_OPEN	RDF	3	4
DISPL_D2	TWR14_XDUCER_FAIL	RDF	3	10
\$BLANK				
#				
# TIMERS...				
#				
ALIAS	POWER_FAIL_TIMER	TMR	0	

ALIAS	POWER_OK_TIMER	TMR	1
ALIAS	HS_1_FAIL_TIMER	TMR	2
ALIAS	HS_2_FAIL_TIMER	TMR	3
ALIAS	PRESSURE_ON_TIMER	TMR	4
ALIAS	PRESSURE_RUNTIME_TIMER	TMR	5
ALIAS	HS_1_DELAY_TIMER	TMR	6
ALIAS	HS_2_DELAY_TIMER	TMR	7
ALIAS	HS_1_OFF_TIMER	TMR	8
ALIAS	HS_2_OFF_TIMER	TMR	9
ALIAS	LOW_GST_TIMER	TMR	10
ALIAS	LOW_GST_OFF_TIMER	TMR	11
ALIAS	VFD1_COMM_FAIL_TIMER	TMR	12
ALIAS	VFD2_COMM_FAIL_TIMER	TMR	13
ALIAS	VFD1_OK_TIMER	TMR	14
ALIAS	VFD2_OK_TIMER	TMR	15

```
#
# USR VARIABLES...
#
```

ALIAS	HS1_RUNTIME_SECS	USR	0
ALIAS	HS2_RUNTIME_SECS	USR	1
ALIAS	XP1_RUNTIME_SECS	USR	2
ALIAS	XP2_RUNTIME_SECS	USR	3
ALIAS	LEAD_PUMP_DEF	USR	4
ALIAS	LAG_PUMP_DEF	USR	5
ALIAS	LASTCALL_TIME	USR	6
ALIAS	DELTA_TIME	USR	7
ALIAS	TOWER_LEAD	USR	8
ALIAS	PRESSURE_LEAD	USR	9
ALIAS	TIMER_LEAD	USR	10
ALIAS	NEW_LEAD_STATE	USR	11
ALIAS	LEAD_TURNING_ON	USR	12
ALIAS	LEAD_TURNING_OFF	USR	13
ALIAS	LEAD_STATE	USR	14
ALIAS	LAG_STATE	USR	15
ALIAS	LOCAL_P1	USR	16
ALIAS	LOCAL_P2	USR	17
ALIAS	TOWER_CONTROL_FAIL	USR	18
ALIAS	SEQUENCE_POINTER_1	USR	19
ALIAS	SEQUENCE_POINTER_2	USR	20
ALIAS	TRY_1_FAIL	USR	21
ALIAS	TRY_2_FAIL	USR	22
ALIAS	AOK	USR	23
ALIAS	P1_FINAL	USR	24
ALIAS	P2_FINAL	USR	25
ALIAS	INFL_FLOWING_USR	USR	26
ALIAS	EFFL_FLOWING_USR	USR	27
ALIAS	PUMP_FAIL_NOW_USR	USR	28
ALIAS	DETENTION_WORKING_USR	USR	29
ALIAS	LEAD_TIMER	USR	30

ALIAS	INFL_EMETER_FAULT_USR	USR	31
ALIAS	INFL_METER_FAULT_USR	USR	32
ALIAS	EFFL_EMETER_FAULT_USR	USR	33
ALIAS	EFFL_METER_FAULT_USR	USR	34
ALIAS	ALL_XDUCER_FAIL	USR	35
ALIAS	COMM_TO_ALL_TOWERS	USR	36
ALIAS	HS1_CONTROL_FB	USR	37
ALIAS	HS1_REF1_FB	USR	38
ALIAS	HS1_REF2_FB	USR	39
ALIAS	HS1_STATUS_FB	USR	40
ALIAS	HS1_SPEED_FB	USR	41
ALIAS	HS1_AMPS_FB	USR	42
ALIAS	HS1_TORQUE_FB	USR	43
ALIAS	HS1_POWER_FB	USR	44
ALIAS	HS1_BUSV_FB	USR	45
ALIAS	HS1_LFAULT_FB	USR	46
ALIAS	HS1_OUTV_FB	USR	47
ALIAS	HS1_TEMP_FB	USR	48
ALIAS	HS2_CONTROL_FB	USR	49
ALIAS	HS2_REF1_FB	USR	50
ALIAS	HS2_REF2_FB	USR	51
ALIAS	HS2_STATUS_FB	USR	52
ALIAS	HS2_SPEED_FB	USR	53
ALIAS	HS2_AMPS_FB	USR	54
ALIAS	HS2_TORQUE_FB	USR	55
ALIAS	HS2_POWER_FB	USR	56
ALIAS	HS2_BUSV_FB	USR	57
ALIAS	HS2_LFAULT_FB	USR	58
ALIAS	HS2_OUTV_FB	USR	59
ALIAS	HS2_TEMP_FB	USR	60
ALIAS	CW_1	USR	61
ALIAS	CW_2	USR	62
ALIAS	CW_3	USR	63
ALIAS	CW_4	USR	64
ALIAS	CW_5	USR	65
ALIAS	CW_STATE	USR	66
ALIAS	VIRTUAL_SPEED_FB	USR	67
ALIAS	CW_EXT1	USR	68
ALIAS	CW_EXT2	USR	69
ALIAS	HS1_SSR_USR	USR	70
ALIAS	HS2_SSR_USR	USR	71

\$NCL

```
# NCL Program
#
# Station : Water Treatment Plant
# Author  : Jim Mimplitz, Navionics Research Inc.
#
```

LBL MAIN

```
# IF FIRSTRUN, INITIALIZE VARIABLES AND TIMERS ...
```

```

FIRSTRUN?
IF FALSE
GOTO      9

GOSUB     SANITY_CHECKS

GOSUB     MY_HS_SEQUENCE_SETUP
LOAD      LEAD_PUMP_DEF
PSTORE    LEAD_HI_SVC_PUMP

LOAD      0
STORE     HI_SVC_PUMP_1_FAIL
STORE     HI_SVC_PUMP_2_FAIL
STORE     TRY_1_FAIL
STORE     TRY_2_FAIL
STORE     HS_1_FAIL_TIMER
STORE     HS_2_FAIL_TIMER
STORE     VFD1_COMM_FAIL_TIMER
STORE     VFD2_COMM_FAIL_TIMER
STORE     HS1_SSR_USR
STORE     HS2_SSR_USR
STORE     VFD1_OK_TIMER
STORE     VFD2_OK_TIMER
POP

LOAD      15
SDELAY    VFD1_OK_TIMER
SDELAY    VFD2_OK_TIMER
POP

LOAD      180
SDELAY    HS_1_OFF_TIMER
SDELAY    HS_2_OFF_TIMER
POP

LOAD      10.0
PSDELAY   POWER_FAIL_TIMER
LOAD      300.0
PSDELAY   POWER_OK_TIMER

LOAD      600.0
PSDELAY   PRESSURE_ON_TIMER

LOAD      20.0
SDELAY    HS_1_DELAY_TIMER
SDELAY    HS_2_DELAY_TIMER
POP

LOAD      420.0
SDELAY    HS_1_FAIL_TIMER
SDELAY    HS_2_FAIL_TIMER
POP

LOAD      60
SDELAY    VFD1_COMM_FAIL_TIMER
SDELAY    VFD2_COMM_FAIL_TIMER
POP

LOAD      30.0
SDELAY    LOW_GST_TIMER
SDELAY    LOW_GST_OFF_TIMER
POP

```

FROM P.34 OF EFB CONTROL MANUAL

```

# STATE DIAGRAM VALUES...

# CHANGES VFD STATE TO "READY TO SWITCH ON"...
    LOAD      0x0006
    PSTORE    CW_1

# CHANGES VFD STATE TO "READY TO OPERATE"...
    LOAD      0x0007
    PSTORE    CW_2

# CHANGES VFD STATE TO "OPERATION ENABLED"
# VFD STARTS, BUT WILL NOT ACCELERATE...
    LOAD      0x000F
    PSTORE    CW_3

# RELEASES RAMP FUNCTION GENERATOR OUTPUT.
# CHANGES VFD STATE TO "RFG: ACCELERATOR ENABLED"...
    LOAD      0x002F
    PSTORE    CW_4

# RELEASES THE RAMP FUNCTION GENERATOR OUTPUT.
# CHANGES VFD STATE TO "OPERATING".
# THE VFD ACCELERATES TO THE GIVEN REFERENCE, AND
# FOLLOWS THE REFERENCE...
    LOAD      0x006F
    PSTORE    CW_5

# CONTROL WORD THAT ENABLES EXT1 CONTROL (DI1 & AIN1)
# AND EXT2 (MODBUS)...

    LOAD      0x0000
    PSTORE    CW_EXT1

    LOAD      0x0800
    PSTORE    CW_EXT2

9    POP

    FIRSTRUN?
    NEW_SETPOINTS?
    |
    IF_FALSE
    GOTO      10

    GOSUB     SANITY_CHECKS
    GOSUB     MY_HS_SEQUENCE_SETUP
    LOAD      LEAD_PUMP_DEF
    PSTORE    LEAD_HI_SVC_PUMP

    LOAD      PRESSURE_MODE_RUNTIME_HRS
    LOAD      3600.0
    *
    PSDELAY   PRESSURE_RUNTIME_TIMER

10   POP

# RESET VFD'S, IF REQUESTED...

    NEW_SETPOINTS?
    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      HI_SVC1_RESET_ONESHOT
    &
    &

```

```

        IF_FALSE
        GOTO      15

# SET FAULT_RESET_SEL TO COMM...
LOAD      8
PSTORE   M_SOU  11  1603

LOAD      0X0080
PSTORE   M_SOU  11  0
LOAD      200
DELAY_MS
LOAD      CW_1
PSTORE   M_SOU  11  0
LOAD      200
DELAY_MS
LOAD      CW_2
PSTORE   M_SOU  11  0

# SET FAULT_RESET_SEL TO KEYPAD...
LOAD      0
PSTORE   M_SOU  11  1603

LOAD      0
PSTORE   HI_SVC1_RESET_ONESHOT
15 POP

NEW_SETPOINTS?
LOAD      HI_SVC_VFD_NETWORKING
LOAD      HI_SVC2_RESET_ONESHOT
&
&
IF_FALSE
GOTO      16

# SET FAULT_RESET_SEL TO COMM...
LOAD      8
PSTORE   M_SOU  12  1603

LOAD      0X0080
PSTORE   M_SOU  12  0
LOAD      200
DELAY_MS
LOAD      CW_1
PSTORE   M_SOU  12  0
LOAD      200
DELAY_MS
LOAD      CW_2
PSTORE   M_SOU  12  0

# SET FAULT_RESET_SEL TO KEYPAD...
LOAD      0
PSTORE   M_SOU  12  1603

LOAD      0
PSTORE   HI_SVC2_RESET_ONESHOT
16 POP

# READ MODBUS INPUT MODULES...

# EIG SHARK VOLTAGE METERS, MODBUS...
# ALIAS  UTIL_AB_IMOD          M_FI  20  0x03ED
# ALIAS  UTIL_BC_IMOD          M_FI  20  0x03EF

```

```
# ALIAS UTIL_CA_IMOD M_FI 20 0x03F1
# SHARK KSB VOLTAGES...
# MODBUS BLOCK TRANSFERS...
# LOADM <DEVICE ID> <INDEX-40001> <N_REGISTERS_TO_READ>
```

```
LOADM 20 0x03ED 6
```

```
CAST_FLOAT 0
PSTORE UTIL_AB_VOLTS
```

```
CAST_FLOAT 2
PSTORE UTIL_BC_VOLTS
```

```
CAST_FLOAT 4
PSTORE UTIL_CA_VOLTS
```

```
# MODBUS BLOCK TRANSFERS...
# LOADM <DEVICE ID> <INDEX-40001> <N_REGISTERS_TO_READ>
```

```
# MODBUS DEVICE 4...
# INFLUENT FLOW METER...
```

```
LOADM 4 0 20
```

```
CAST_ULONG 0
LOAD 10.0
*
PSTORE INFL_METER_GAL
```

```
CAST_LONG 4
LOAD 0.001
*
PSTORE INFL_FLOW_GPM
```

```
CAST_INT 14
PSTORE INFL_METER_FAULT_USR
```

```
MA_VLD
!
PSTORE INFL_EMETER_FAULT_USR
```

```
# MODBUS DEVICE 5...
# EFFLUENT FLOW METER, PROCESS FLOW METER...
```

```
LOADM 5 0 20
```

```
CAST_ULONG 0
LOAD 10.0
*
PSTORE EFFL_METER_GAL
```

```
CAST_ULONG 2
PSTORE PROCESS_METER_GAL
```

```
CAST_LONG 4
LOAD 0.001
*
PSTORE EFFL_FLOW_GPM
```

```
CAST_LONG 6
LOAD 0.001
*
```

```

PSTORE      PROCESS_FLOW_GPM

CAST_INT    14
PSTORE      EFFL_METER_FAULT_USR

MA_VLD
!
PSTORE      EFFL_EMETER_FAULT_USR

```

```
# SINGLE-REGISTER MODBUS READS FROM KELLER TRANSDUCERS...
```

```

LOAD        EFFL_PSI_MODULE
LOAD        14.5037744
*
PSTORE      EFFL_PSI
MA_VLD
!
PSTORE      EFFL_XDUCER_FAIL

LOAD        GST_PSI_MODULE
LOAD        14.5037744
*
LOAD        2.3067
*
LOAD        2.45833
+
STORE       GST_FT
LOAD        28.0
/
LOAD        1000.0
*
PSTORE      GST_KGAL
MA_VLD
!
PSTORE      GST_XDUCER_FAIL

LOAD        CLEARWELL_PSI_MODULE
LOAD        14.5037744
*
LOAD        2.3067
*
LOAD        3.0
+
STORE       CLEARWELL_FT
LOAD        10.0
/
LOAD        150.0
*
PSTORE      CLEARWELL_KGAL
MA_VLD
!
PSTORE      CLEARWELL_XDUCER_FAIL

```

```
# READ DATA FROM VFD 1...
```

```

LOAD        HI_SVC_VFD_NETWORKING
LOAD        VFD1_OK_TIMER
&
IF_FALSE
GOTO        210
LOADM       11    0    4

```

```
# CONTROL WORD...
```

```

        CAST_UINT    0
        PSTORE       HS1_CONTROL_FB
# REFERENCE 1...
        CAST_UINT    1
        PSTORE       HS1_REF1_FB
# REFERENCE 2...
        CAST_UINT    2
        PSTORE       HS1_REF2_FB
# STATUS WORD...
        CAST_UINT    3
        PSTORE       HS1_STATUS_FB

        LOADM        11  102  10
# SPEED (HZ) x 10...
        CAST_UINT    0
        LOAD         600
        /
        LOAD         100
        *
        PSTORE       HS1_SPEED_FB
# CURRENT (A) X 10...
        CAST_UINT    1
        LOAD         0.1
        *
        PSTORE       HS1_AMPS_FB
# TORQUE (%) x 10...
        CAST_UINT    2
        LOAD         0.1
        *
        PSTORE       HS1_TORQUE_FB
# POWER (KW) x 10...
        CAST_UINT    3
        LOAD         0.1
        *
        PSTORE       HS1_POWER_FB
# DC BUS (V)...
        CAST_UINT    4
        PSTORE       HS1_BUSV_FB
# OUTPUT VOLTAGE (V)...
        CAST_UINT    5
        PSTORE       HS1_OUTV_FB
# TRANSISTOR TEMP (C) x 10...
        CAST_UINT    6
        LOAD         0.18
        *
        LOAD         32
        +
        PSTORE       HS1_TEMP_FB

        LOADM        11  400  1
# LAST FAULT...
        CAST_UINT    0
        PSTORE       HS1_LFAULT_FB

        MA_VLD
        !
        PSTORE       VFD1_COMM_FAIL_TIMER

210  POP

        LOAD         HS1_SSR
        LOAD         HS1_FB_MODULE
        |
        IF_TRUE

```

```

GOTO      211
LOAD      0
STORE     HS1_POWER_FB
STORE     HS1_SPEED_FB
STORE     HS1_AMPS_FB
STORE     HS1_TORQUE_FB
STORE     HS1_POWER_FB
STORE     HS1_BUSV_FB
STORE     HS1_OUTV_FB
POP
LOAD      32
PSTORE   HS1_TEMP_FB
211      POP

LOAD      HS1_POWER_FB
PSTORE   HI_SVC1_KW

LOAD      HS1_TEMP_FB
PSTORE   HI_SVC1_DEGF

LOAD      EFFL_FLOW_GPM
LOAD      60
*
LOAD      HI_SVC1_KW
LOAD      0.1
MAX
/
LOAD      HI_SVC1_KW
!
!
*
PSTORE   HI_SVC1_GPK

LOAD      HS1_STATUS_FB
BITMASK  3
LOAD      HS1_LFAULT_FB
*
PSTORE   HI_SVC1_FAULT_CODE

LOAD      HI_SVC_VFD_NETWORKING
LOAD      HS1_SSR
LOAD      HS1_FB_MODULE
|
&
LOAD      VFD1_COMM_FAIL_TIMER
&
PSTORE   HI_SVC1_VFD_COMM_FAIL

# READ DATA FROM VFD 2...

LOAD      HI_SVC_VFD_NETWORKING
LOAD      VFD2_OK_TIMER
&
IF_FALSE
GOTO      220
LOADM     12    0    4
# CONTROL WORD...
CAST_UINT 0
PSTORE   HS2_CONTROL_FB
# REFERENCE 1...
CAST_UINT 1
PSTORE   HS2_REF1_FB

```



```

# REFERENCE 2...
    CAST_UINT    2
    PSTORE       HS2_REF2_FB
# STATUS WORD...
    CAST_UINT    3
    PSTORE       HS2_STATUS_FB

    LOADM       12  102  10
# SPEED (HZ) x 10...
    CAST_UINT    0
    LOAD         600
    /
    LOAD         100
    *
    PSTORE       HS2_SPEED_FB
# CURRENT (A) X 10...
    CAST_UINT    1
    LOAD         0.1
    *
    PSTORE       HS2_AMPS_FB
# TORQUE (%) x 10...
    CAST_UINT    2
    LOAD         0.1
    *
    PSTORE       HS2_TORQUE_FB
# POWER (KW) x 10...
    CAST_UINT    3
    LOAD         0.1
    *
    PSTORE       HS2_POWER_FB
# DC BUS (V)...
    CAST_UINT    4
    PSTORE       HS2_BUSV_FB
# OUTPUT VOLTAGE (V)...
    CAST_UINT    5
    PSTORE       HS2_OUTV_FB
# TRANSISTOR TEMP (C) x 10...
    CAST_UINT    6
    LOAD         0.18
    *
    LOAD         32
    +
    PSTORE       HS2_TEMP_FB

    LOADM       12  400  1
# LAST FAULT...
    CAST_UINT    0
    PSTORE       HS2_LFAULT_FB

    MA_VLD
    !
    PSTORE       VFD2_COMM_FAIL_TIMER

220  POP

    LOAD         HS2_SSR
    LOAD         HS2_FB_MODULE
    |
    IF TRUE
    GOTO         221
    LOAD         0
    STORE        HS2_POWER_FB
    STORE        HS2_SPEED_FB
    STORE        HS2_AMPS_FB

```

```

STORE      HS2_TORQUE_FB
STORE      HS2_POWER_FB
STORE      HS2_BUSV_FB
STORE      HS2_OUTV_FB
POP
LOAD      32
PSTORE    HS2_TEMP_FB
POP

LOAD      HS2_POWER_FB
PSTORE    HI_SVC2_KW

LOAD      HS2_TEMP_FB
PSTORE    HI_SVC2_DEGF

LOAD      EFFL_FLOW_GPM
LOAD      60
*
LOAD      HI_SVC2_KW
LOAD      0.1
MAX
/
LOAD      HI_SVC2_KW
!
!
*
PSTORE    HI_SVC2_GPK

LOAD      HS2_STATUS_FB
BITMASK   3
LOAD      HS2_LFAULT_FB
*
PSTORE    HI_SVC2_FAULT_CODE

LOAD      HI_SVC_VFD_NETWORKING
LOAD      HS2_SSR
LOAD      HS2_FB_MODULE
|
&
LOAD      VFD2_COMM_FAIL_TIMER
&
PSTORE    HI_SVC2_VFD_COMM_FAIL

```

READ GRAYHILL I/O MODULES...

```

LOAD      POWER_OK_MODULE
!
PSTORE    POWER_FAIL_TIMER
LOAD      POWER_FAIL_TIMER
!
PSTORE    POWER_OK_TIMER
LOAD      POWER_OK_TIMER
PSTORE    POWER

LOAD      INFL_FLOW_GPM
LOAD      INFL_FLOW_DETECT_GPM
Y>=X?
LOAD      INFL_METER_FAULT_USR
LOAD      INFL_EMETER_FAULT_USR
|
PSTORE    INFL_FLOWING_USR

```

```

LOAD      EFFL_FLOW_GPM
LOAD      EFFL_FLOW_DETECT_GPM
Y>=X?
LOAD      EFFL_METER_FAULT_USR
LOAD      EFFL_EMETER_FAULT_USR
|
PSTORE    EFFL_FLOWING_USR

LOAD      HS1_FB_MODULE
LOAD      EFFL_FLOWING_USR
&
PSTORE    HI_SVC_PUMP_1

LOAD      HS2_FB_MODULE
LOAD      EFFL_FLOWING_USR
&
PSTORE    HI_SVC_PUMP_2

LOAD      XF1_FB_MODULE
PSTORE    XFER_PUMP_1

LOAD      XF2_FB_MODULE
PSTORE    XFER_PUMP_2

LOAD      GEN_FB_MODULE
!
PSTORE    GENERATOR

LOAD      GEN_LOFUEL_MODULE
PSTORE    GENERATOR_LO_FUEL

# ASSIGN LEAD HI SVC PUMP DEF...

LOAD      LEAD_PUMP_DEF
PSTORE    LEAD_HI_SVC_PUMP

# TIME CALCULATOR ...

SYTIME
LOAD      LASTCALL_TIME
-
PSTORE    DELTA_TIME
SYTIME
PSTORE    LASTCALL_TIME

# SYSTEM UPTIME CALCULATOR ...

UPTIME
LOAD      60.0
/
PSTORE    RTU_UPTIME_MIN

# COMM HANDLER...

LOAD      COMM_TO_TWR01
!
LOAD      COMM_TO_TWR13

```

```

!
LOAD      COMM_TO_TWR14
!
&
&
!
PSTORE   COMM_TO_ALL_TOWERS

LOAD      TWR01_XDUCER_FAIL
LOAD      COMM_TO_TWR01
&
LOAD      TWR13_XDUCER_FAIL
LOAD      COMM_TO_TWR13
&
LOAD      TWR14_XDUCER_FAIL
LOAD      COMM_TO_TWR14
&
&
&
PSTORE   ALL_XDUCER_FAIL

LOAD      COMM_TO_TWR01
LOAD      COMM_TO_TWR13
LOAD      COMM_TO_TWR14
&
&
!
PSTORE   COMM_FAIL_TO_TOWERS

```

LAKE INTAKE HANDLER...

```

LOAD      CALL_INTAKE_1{OFF-ON}
LOAD      2.0
Y=X?
PSTORE   CALL_INTAKE_1

LOAD      CALL_INTAKE_2{OFF-ON}
LOAD      2.0
Y=X?
PSTORE   CALL_INTAKE_2

```

BPS_MODE_CALC ...

```

LOADA    HI_SVC_MODE{RADIO-PRESS-TIMER}
LOADA    HI_SVC_FAILOVER{PRESS-TIMER}
LOADA    COMM_TO_ALL_TOWERS
LOADA    ALL_XDUCER_FAIL
MACRO    BPS_MODE_CALC
POP
PSTORE   TIMER_MODE
LOAD     EFFL_XDUCER_FAIL
!
&
PSTORE   PRESSURE_MODE
PSTORE   RADIO_MODE

```

TIMER HANDLER ...

```

LOAD      TIMER_1_START_HOUR

```

```

LOAD      TIMER_1_STOP_HOUR
BETWEEN_HOURS
LOAD      TIMER_2_START_HOUR
LOAD      TIMER_2_STOP_HOUR
BETWEEN_HOURS
LOAD      TIMER_3_START_HOUR
LOAD      TIMER_3_STOP_HOUR
BETWEEN_HOURS
|
LOAD      TIMER_MODE
&
PSTORE   TIMER_LEAD

```

TOWER HANDLER...

```

LOAD      TWR01_CALL_PLANT
LOAD      TWR01_VALVE_OPEN
LOAD      COMM_TO_TWR01
&
&
LOAD      TWR13_CALL_PLANT
LOAD      TWR13_VALVE_OPEN
LOAD      COMM_TO_TWR13
&
&
LOAD      TWR14_CALL_PLANT
LOAD      TWR14_VALVE_OPEN
LOAD      COMM_TO_TWR14
&
&
|
LOAD      TWR01_FULL
!
LOAD      TWR01_VALVE_OPEN
LOAD      COMM_TO_TWR01
&
&
LOAD      TWR13_FULL
!
LOAD      TWR13_VALVE_OPEN
LOAD      COMM_TO_TWR13
&
&
LOAD      TWR14_FULL
!
LOAD      TWR14_VALVE_OPEN
LOAD      COMM_TO_TWR13
&
&
|
LOAD      TOWER_LEAD
&
|
LOAD      RADIO_MODE
&
PSTORE   TOWER_LEAD

```

PRESSURE-LEAD HANDLER ...

```

LOAD      PUMP_FAIL_NOW_USR
IF_FALSE
GOTO     354
TIMEOUT  PRESSURE_RUNTIME_TIMER
LOAD     0.0
PSTORE   PRESSURE_ON_TIMER
354      POP

```

```

LOADA    EFFL_PSI
LOADA    PRESSURE_MODE_ON_PSI
LOADA    PRESSURE_ON_TIMER
LOADA    PRESSURE_RUNTIME_TIMER
MACRO    HYBRID_PRESSURE_LO
LOAD     PRESSURE_MODE
&
PSTORE   PRESSURE_LEAD

```

```
# LEAD_STATE CALC ...
```

```

LOAD     TOWER_LEAD
LOAD     PRESSURE_LEAD
LOAD     TIMER_LEAD
|
|
STORE    NEW_LEAD_STATE
LOAD     LEAD_STATE
!
&
STORE    LEAD_TURNING_ON
LOAD     NEW_LEAD_STATE
!
LOAD     LEAD_STATE
&
STORE    LEAD_TURNING_OFF
|
IF_FALSE
GOTO     40
LOAD     0
PSTORE   LEAD_TIMER
40      POP

```

```

LOAD     NEW_LEAD_STATE
PSTORE   LEAD_STATE

```

```
# LOCAL_P1 & LOCAL_P2 CALC ...
```

```

LOAD     LEAD_STATE
LOAD     LEAD_PUMP_DEF
LOAD     1.0
X=Y?
&
PSTORE   LOCAL_P1

LOAD     LEAD_STATE
LOAD     LEAD_PUMP_DEF
LOAD     2.0
X=Y?
&
PSTORE   LOCAL_P2

```

LOW GST...

```
LOADA GST_FT
LOADA LOW_GST_FT
LOADA LOW_GST_RELEASE_FT
LOADA LOW_GST_TIMER
LOADA LOW_GST_OFF_TIMER
LOADA LOW_GST
MACRO HYSTERESIS_LO_W_TIMER
LOAD GST_XDUCER_FAIL
!
&
PSTORE LOW_GST
```

AOK CALC...

POWER FAIL OR LOW_GST WILL INHIBIT HI SVC PUMPS.
IF GST XDUCER FAILS, THEN LOW_GST WILL INHIBIT
HI SVC PUMPS.

```
LOAD POWER
LOAD LOW_GST
!
&
PSTORE AOK
```

FINAL P1 CALC ...

```
LOAD LOCAL_P1
LOAD HI_SVC_1{AUTO-ON-OFF}
LOAD 2.0
X=Y?
|
LOAD AOK
&
LOAD HI_SVC_1{AUTO-ON-OFF}
LOAD 3.0
X=Y?
!
&
LOAD HS2_SSR_USR
!
&
PSTORE HS_1_DELAY_TIMER
LOAD HS_1_DELAY_TIMER
STORE P1_FINAL
!
PSTORE HS_1_OFF_TIMER
LOAD HS_1_OFF_TIMER
!
LOAD P1_FINAL
|
PSTORE HS1_SSR

LOAD HS1_SSR
LOAD HS1_FB_MODULE
|
PSTORE VFD1_OK_TIMER
```

FOR ABB VFD'S, THE MODBUS REGISTER FOR A DRIVE
PARAMETER CAN BE DERIVED AS:
MODBUS_ADDR (ZERO-BASED) = DRIVE_PARAM - 1

```

# FOR EXAMPLE, DRIVE_PARAMETER 1002 = MODBUS_ADDR 1001

# HI SVC VFD
# ENABLE NETWORK CONTROL OF DRIVES, IF DESIRED...

#     IF NETWORKING ON...
# AND IF TELEMETRY CALLING FOR PUMP 1...
# AND IF VFD1 IS FULLY BOOTED UP...
# AND IF VFD1 HAS NOT BEEN CONFIGURED...
# THEN CONFIGURE VFD1 FOR COMM OPERATION...

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      HS1_SSR
    &
    LOAD      VFD1_OK_TIMER
    &
    LOAD      HS1_SSR_USR
    !
    &
    IF_FALSE
    GOTO      511

# SET FAULT_RESET_SEL TO COMM...
    LOAD      8
    PSTORE   M_SOU  11  1603
# SET COMM_FAULT_ACTION TO FAULT...
    LOAD      1
    PSTORE   M_SOU  11  3017

# PREP VFD BY STEPPING THROUGH NECESSARY STATES...
    LOAD      0X0080
    PSTORE   M_SOU  11  0
    LOAD      200
    DELAY_MS
    LOAD      CW_1
    PSTORE   M_SOU  11  0
    LOAD      200
    DELAY_MS
    LOAD      CW_2
    PSTORE   M_SOU  11  0

# ASSIGN VALUE TO HS1_SSR_USR
    LOAD      HS1_SSR
    PSTORE   HS1_SSR_USR

# RESET FAULT_RESET_SEL TO KEYPAD...
    LOAD      0
    PSTORE   M_SOU  11  1603

511  POP

# THIS SHOULD BE RUN IF NETWORKING IS ON,
# IN ORDER TO TURN ON OR OFF VFD1...

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      VFD1_OK_TIMER
    &
    IF_FALSE
    GOTO      512

    LOAD      HS1_SSR
    LOAD      CW_5
    LOAD      CW_EXT2

```



```

+
LOAD      CW_2
-
*
LOAD      CW_2
+
PSTORE   M_SOU  11  0

512  POP

# PUMP 1 IS ON, BUT RTU IS NOT CALLING FOR IT.
# CONFIGURE FOR MANUAL MODE...

      LOAD      HI_SVC_VFD_NETWORKING
      LOAD      VFD1_OK_TIMER
      &
      LOAD      HS1_SSR
      !
      &
      IF_FALSE
      GOTO      513
# SET FAULT_RESET_SEL TO KEYPAD...
      LOAD      0
      PSTORE   M_SOU  11  1603
# SET COMM_FAULT_ACTION TO NO_ACTION...
      LOAD      0
      PSTORE   M_SOU  11  3017
513  POP

# VFD1 IS OFF. NEED TO ZERO OUT HS1_SSR_USR...
# IF HS1_SSR IS OFF, THEN ZERO OUT HS1_SSR_USR

      LOAD      HS1_SSR_USR
      LOAD      HS1_SSR
      &
      PSTORE   HS1_SSR_USR

# P1 FAIL CALC ...

      LOAD      HS1_SSR
      LOAD      HI_SVC_PUMP_1
      XOR
      PSTORE   HS_1_FAIL_TIMER
      LOAD      HS_1_FAIL_TIMER
      STORE    TRY_1_FAIL
      LOAD      HI_SVC_PUMP_1_FAIL
      LOAD      HI_SVC_PUMP_1
      !
      &
      |
      PSTORE   HI_SVC_PUMP_1_FAIL

# FINAL P2 CALC ...

      LOAD      LOCAL_P2
      LOAD      HI_SVC_2{AUTO-ON-OFF}
      LOAD      2.0
      X=Y?

```

```

|
LOAD      AOK
&
LOAD      HI_SVC_2{AUTO-ON-OFF}
LOAD      3.0
X=Y?
!
&
LOAD      HS1_SSR_USR
!
&
PSTORE   HS_2_DELAY_TIMER
LOAD     HS_2_DELAY_TIMER
STORE    P2_FINAL
!
PSTORE   HS_2_OFF_TIMER
LOAD     HS_2_OFF_TIMER
!
LOAD     P2_FINAL
|
PSTORE   HS2_SSR

LOAD     HS2_SSR
LOAD     HS2_FB_MODULE
|
PSTORE   VFD2_OK_TIMER

# FOR ABB VFD'S, THE MODBUS REGISTER FOR A DRIVE
# PARAMETER CAN BE DERIVED AS:
# MODBUS_ADDR (ZERO-BASED) = DRIVE_PARAM - 1
# FOR EXAMPLE, DRIVE_PARAMETER 1002 = MODBUS_ADDR 1001

# HI SVC VFD
# ENABLE NETWORK CONTROL OF DRIVES, IF DESIRED...

# IF NETWORKING ON...
# AND IF TELEMETRY CALLING FOR PUMP 2...
# AND IF VFD2 IS FULLY BOOTED UP...
# AND IF VFD2 HAS NOT BEEN CONFIGURED...
# THEN CONFIGURE VFD2 FOR COMM OPERATION...

LOAD     HI_SVC_VFD_NETWORKING
LOAD     HS2_SSR
&
LOAD     VFD2_OK_TIMER
&
LOAD     HS2_SSR_USR
!
&
IF_FALSE
GOTO     611
# SET FAULT_RESET_SEL TO COMM...
LOAD     8
PSTORE   M_SOU 12 1603
# SET COMM_FAULT_ACTION TO FAULT...
LOAD     1
PSTORE   M_SOU 12 3017

# PREP VFD BY STEPPING THROUGH NECESSARY STATES...
LOAD     0X0080
PSTORE   M_SOU 12 0
LOAD     200

```

```

    DELAY_MS
    LOAD      CW_1
    PSTORE    M_SOU  12  0
    LOAD      200
    DELAY_MS
    LOAD      CW_2
    PSTORE    M_SOU  12  0

# RESET FAULT_RESET_SEL TO KEYPAD...
    LOAD      0
    PSTORE    M_SOU  12  1603

# ASSIGN VALUE TO HS2_SSR_USR
    LOAD      HS2_SSR
    PSTORE    HS2_SSR_USR

611  POP

# THIS SHOULD BE RUN IF NETWORKING IS ON,
# IN ORDER TO TURN ON OR OFF VFD2...

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      VFD2_OK_TIMER
    &
    IF_FALSE
    GOTO      612

    LOAD      HS2_SSR
    LOAD      CW_5
    LOAD      CW_EXT2
    +
    LOAD      CW_2
    -
    *
    LOAD      CW_2
    +
    PSTORE    M_SOU  12  0

612  POP

# PUMP 2 IS ON, BUT RTU IS NOT CALLING FOR IT.
# CONFIGURE FOR MANUAL MODE...

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      VFD2_OK_TIMER
    &
    LOAD      HS2_SSR
    !
    &
    IF_FALSE
    GOTO      613
# SET FAULT_RESET_SEL TO KEYPAD...
    LOAD      0
    PSTORE    M_SOU  12  1603
# SET COMM_FAULT_ACTION TO NO_ACTION...
    LOAD      0
    PSTORE    M_SOU  12  3017

613  POP

# VFD2 IS OFF. NEED TO ZERO OUT HS2_SSR_USR...

```

```

# IF HS2_SSR IS OFF, THEN ZERO OUT HS2_SSR_USR

    LOAD      HS2_SSR_USR
    LOAD      HS2_SSR
    &
    PSTORE    HS2_SSR_USR

# P2 FAIL CALC ...

    LOAD      HS2_SSR
    LOAD      HI_SVC_PUMP_2
    XOR
    PSTORE    HS_2_FAIL_TIMER
    LOAD      HS_2_FAIL_TIMER
    STORE     TRY_2_FAIL
    LOAD      HI_SVC_PUMP_2_FAIL
    LOAD      HI_SVC_PUMP_2
    !
    &
    |
    PSTORE    HI_SVC_PUMP_2_FAIL

# VFD SPEED CALCULATION...
#
# Note that when the pumps are to be shut down
# (p1_final=0 AND p2_final=0), the discharge pressure
# limit is artificially set to zero. This ensures that
# the speed is tapered down to zero before pump shutdown.
#
# Note that the vfd's are configured for a min speed
# of 20 Hz (33%). Control logic reflects this, too.

# VIRTUAL READ SPEED...

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      HS1_FB_MODULE
    LOAD      HS2_FB_MODULE
    |
    &
    LOAD      HS1_SPEED_FB
    LOAD      HS2_SPEED_FB
    MAX
    *

    LOAD      HI_SVC_VFD_NETWORKING
    LOAD      HS1_FB_MODULE
    LOAD      HS2_FB_MODULE
    |
    &
    !
    LOAD      HI_SVC_VFD_SPEED_%
    *

    MAX
    PSTORE    VIRTUAL_SPEED_FB

# VFD SPEED CALCULATION...
#
# Note that when the pumps are to be shut down

```

```

# (p1_final=0 AND p2_final=0), the discharge pressure
# limit is artificially set to zero. This ensures that
# the speed is tapered down to zero before pump shutdown.
#
# Note that when the station is in GST Mode, the
# suction pressure will be ignored for VFD speed control.
#

```

```

LOAD HI_SVC_VFD_SPEED_%
LOAD HI_SVC_GAIN
LOAD HI_SVC_MAXSTEP
LOAD 0.0
LOAD EFFL_PSI
LOAD 0.0
LOAD EFFL_LIMIT_PSI
LOAD P1_FINAL
LOAD P2_FINAL
|
*
MACRO FEEDBACK_CONTROL
LOAD EFFL_XDUCER_FAIL
!
*
LOAD HI_SVC_FAILOVER_SPEED_%
LOAD EFFL_XDUCER_FAIL
*
+
LOAD HI_SVC_MINSPEED_%
MAX
LOAD HI_SVC_MAXSPEED_%
MIN
LOAD VIRTUAL_SPEED_FB
LOAD HI_SVC_MAXSTEP
LOAD 4
*
+
MIN
LOAD HI_SVC_MINSPEED_%
MAX
LOAD HS1_SSR
LOAD HS2_SSR
|
*
PSTORE HI_SVC_VFD_SPEED_%

LOAD HI_SVC_VFD_SPEED_%
LOAD 100.0
/
LOAD HS1_SSR
*
LOAD HI_SVC_VFD_NETWORKING
!
*
PSTORE HS1_SPEED_MODULE

LOAD HI_SVC_VFD_SPEED_%
LOAD 100.0
/
LOAD HS2_SSR
*
LOAD HI_SVC_VFD_NETWORKING
!
*
PSTORE HS2_SPEED_MODULE

```

```

LOAD      HS1_SSR
LOAD      HI_SVC_VFD_NETWORKING
&
IF_FALSE
GOTO      305
LOAD      HS1_SSR
LOAD      HI_SVC_VFD_SPEED_%
*
LOAD      100
*
PSTORE   M_SOU  11  2
305 POP

```

```

LOAD      HS1_SSR
LOAD      HI_SVC_VFD_NETWORKING
!
&
IF_FALSE
GOTO      306
LOAD      CW_EXT1
PSTORE   M_SOU  11  0
306 POP

```

```

LOAD      HS2_SSR
LOAD      HI_SVC_VFD_NETWORKING
&
IF_FALSE
GOTO      307
LOAD      HS2_SSR
LOAD      HI_SVC_VFD_SPEED_%
*
LOAD      100
*
PSTORE   M_SOU  12  2
307 POP

```

```

LOAD      HS2_SSR
LOAD      HI_SVC_VFD_NETWORKING
!
&
IF_FALSE
GOTO      308
LOAD      CW_EXT1
PSTORE   M_SOU  12  0
308 POP

```

```

# XFER PUMP-1 RUNTIME ...
# (WILL ROLLOVER AFTER ~20 YEARS OF RUNTIME)

```

```

LOAD      XFER_PUMP_1
LOAD      DELTA_TIME
*
LOAD      XP1_RUNTIME_SECS
+
ABS
LOAD      600000000.0
%
STORE    XP1_RUNTIME_SECS
LOAD      60.0
/

```

```

PSTORE    XFER_PUMP_1_RUNTIME_MIN

# XFER PUMP-2 RUNTIME ...
# (WILL ROLLOVER AFTER ~20 YEARS OF RUNTIME)

LOAD      XFER_PUMP_2
LOAD      DELTA_TIME
*
LOAD      XP2_RUNTIME_SECS
+
ABS
LOAD      600000000.0
%
STORE     XP2_RUNTIME_SECS
LOAD      60.0
/
PSTORE    XFER_PUMP_2_RUNTIME_MIN

# PUMP-1 RUNTIME ...
# (WILL ROLLOVER AFTER ~20 YEARS OF RUNTIME)

LOAD      HI_SVC_PUMP_1
LOAD      DELTA_TIME
*
LOAD      HS1_RUNTIME_SECS
+
ABS
LOAD      600000000.0
%
STORE     HS1_RUNTIME_SECS
LOAD      60.0
/
PSTORE    HI_SVC_1_RUNTIME_MIN

# PUMP-2 RUNTIME ...
# (WILL ROLLOVER AFTER ~20 YEARS OF RUNTIME)

LOAD      HI_SVC_PUMP_2
LOAD      DELTA_TIME
*
LOAD      HS2_RUNTIME_SECS
+
ABS
LOAD      600000000.0
%
STORE     HS2_RUNTIME_SECS
LOAD      60.0
/
PSTORE    HI_SVC_2_RUNTIME_MIN

# IF THE LEAD PUMP FAILS, THE LEAD HAS RUN FOR 12 HOURS,
# OR PUMP-A JUST TURNED OFF, INCREMENT ALTERNATOR ...

LOAD      LEAD_TIMER
LOAD      12
Y>X?

LOAD      LEAD_PUMP_DEF
LOAD      1
X=Y?

```

```

LOAD      TRY_1_FAIL
LOAD      HI_SVC_1{AUTO-ON-OFF}
LOAD      3.0
X=Y?
|
&

LOAD      LEAD_PUMP_DEF
LOAD      2
X=Y?
LOAD      TRY_2_FAIL
LOAD      HI_SVC_2{AUTO-ON-OFF}
LOAD      3.0
X=Y?
|
&

|

# FORCE ONLY ONE ALTERNATION ON PUMP FAIL...

COPY
LOAD      LEAD_STATE
&
PSTORE   PUMP_FAIL_NOW_USR

LOAD      LEAD_STATE
&
LOAD      LEAD_TURNING_OFF
|
|
LOAD      ALTERNATE_HI_SVC
&
IF_FALSE
GOTO     110
LOAD     SEQUENCE_POINTER_1
LOAD     2.0
%
++
PSTORE   SEQUENCE_POINTER_1

LOAD     0.0
PSTORE   LEAD_TIMER

GOSUB    MY_HS_SEQUENCE_SETUP
LOAD     LEAD_PUMP_DEF
PSTORE   LEAD_HI_SVC_PUMP

110      POP

# INCREMENT LEAD TIMER ...

LOAD     LEAD_STATE
IF_FALSE
GOTO     555
LOAD     LEAD_TIMER
LOAD     DELTA_TIME
LOAD     3600
/
+
PSTORE   LEAD_TIMER

```


FORCE ONLY ONE PUMP ALTERNATION UPON PUMP FAIL...

```

LOAD      LEAD_STATE
LOAD      PUMP_FAIL_NOW_USR
!
&
PSTORE    LEAD_STATE

```

END

LBL SANITY_CHECKS

```

LOAD      2.0
LOAD      1.0
LOAD      SEQUENCE_POINTER_1
MAX
MIN
PSTORE    SEQUENCE_POINTER_1

```

```

LOAD      2.0
LOAD      1.0
LOAD      LEAD_HI_SVC{P1-P2}
MAX
MIN
PSTORE    LEAD_HI_SVC{P1-P2}

```

```

LOAD      2.0
LOAD      1.0
LOAD      LAG_HI_SVC{P1-P2}
MAX
MIN
PSTORE    LAG_HI_SVC{P1-P2}

```

```

LOAD      2.0
LOAD      1.0
LOAD      CALL_INTAKE_1{OFF-ON}
MAX
MIN
PSTORE    CALL_INTAKE_1{OFF-ON}

```

```

LOAD      2.0
LOAD      1.0
LOAD      CALL_INTAKE_2{OFF-ON}
MAX
MIN
PSTORE    CALL_INTAKE_2{OFF-ON}

```

```

LOAD      3.0
LOAD      1.0
LOAD      HI_SVC_1{AUTO-ON-OFF}
MAX
MIN
PSTORE    HI_SVC_1{AUTO-ON-OFF}

```

```

LOAD      3.0

```

```

LOAD      1.0
LOAD      HI_SVC_2{AUTO-ON-OFF}
MAX
MIN
PSTORE   HI_SVC_2{AUTO-ON-OFF}

LOAD      3
LOAD      1
LOAD      HI_SVC_MODE{RADIO-PRESS-TIMER}
MAX
MIN
PSTORE   HI_SVC_MODE{RADIO-PRESS-TIMER}

LOAD      3
LOAD      1
LOAD      HI_SVC_FAILOVER{PRESS-TIMER}
MAX
MIN
PSTORE   HI_SVC_FAILOVER{PRESS-TIMER}

RTN

# =====

LBL       MY_HS_SEQUENCE_SETUP

LOADA     ALTERNATE_HI_SVC
LOADA     SEQUENCE_POINTER_1
LOADA     LEAD_HI_SVC{P1-P2}
LOADA     LAG_HI_SVC{P1-P2}
LOADA     LEAD_PUMP_DEF
LOADA     LAG_PUMP_DEF
MACRO     PUMP_SEQUENCE_SETUP2
RTN

# =====

```